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Adapting project management method and ANFIS strategy for variables selection and analyzing wind turbine wake effect

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Abstract We present a project management methodology signed for the selection of wind turbines wake effect most influential parameters, who nee orun wind farm project for large energy conversion. Very frequently, the manage of these projects are not project management professionals, so they need guidance to have autonomy, using minimal time and documentation resources. Therefore, agile method is adapted to assist the project management. Wind energy poses challenges such . the reduction in the wind speed due to the wake effect by other turbines. If a turbine is we hin the area of turbulence caused by another turbine, or the area behind another turbin, the wind speed suffers a reduction and, therefore, there is a decrease in the pottetion of electricity. In order to increase the efficiency of a wind farm, analyzing the parameters, which have influence on the wake effect, is one of the focal research at To maximize the power produced in a wind farm, it is important to determine and analyze the most influential factors on the wake effects or wake wind speeds since the ffect has most influence on the produced power. This procedure is typically called variable selection, and it corresponds to finding a subset of the full set of recorded variable. That exhibits good predictive abilities. In this study, architecture for modeling complex systems in function approximation and regression was used, based on using device neuro-fuzzy inference system (ANFIS). Variable searching using the ANFI network was performed to determine how the five parameters affect the wake wind speed. Our article answers the call for renewing the theoretical bases of wind farm project mana, ement in order to overcome the problems that stem from the application of me as based on decision-rationality norms, which bracket the complexity of action and iterations in projects.

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1 Introduction

The project management field experiences a revolution with two main drivers. The first driver is a practical reconsideration of prescriptions rooted in the rationality of decisit theory, which seem to generate technical and commercial failures, internal and external conflicts, and inadequate responses to unexpected events. Project practitioners res, and to these shortcomings by proposing new approaches, such as agile methods or particing approaches, anchored in different rationalities. Researchers aim to better account for project phenomena and outcomes by redirecting efforts away from developing minimizing plans, contracts and charts, and toward understanding the specific nature of social relations, structures, and processes that occur in projects. In particular, they seek to draw upon fundamental sociological theories in order to detain the inderstanding of project organizations. We present a project management method in the inderstanding of the selection of wind turbines wake effect most influential paremeters, who need to run wind farm project for large energy conversion.

Renewable energy sources have attracted lots of attention due to the technology development, their no dependence on fossil fuels and their friendliness to the environment. The relative low values of the wind turbine-r ed c. acities available nowadays, compared to conventional power station units, mean that hig number of turbines must be installed in a single site, a wind station or wind farm, in order to reach an installed capacity similar to a conventional power station. This with turb ne cluster disposition, more or less packed, offers some economic advantages lated to the investment and to the plant operation and maintenance costs (Grady et 2. 2005, But the wind turbine compactness degree is limited by spacing constrains due to wind shadow or wake decay effects (Marmidis et al. 2008), that is, when two wind turbines are placed too close one behind the other in the prevailing wind direction, the to amount of generated power is less than the initially expected individual power sum at u. free air stream because the wind power in the air stream available for the own vind turbine is reduced due to the wind power extracted by the upwind rotor to bar. Jonzalez et al. 2010; Changshui et al. 2011). As a consequence, the layout or pecific idividual wind turbine position determines the overall potential wind energy ext. ion efficiency of a wind farm (Ekonomou et al. 2012; Saavedra-Moreno et al. 20'1; Eroglu and Seckiner 2012; Yin and Wang 2012). The wind turbine wake effect dep. As or several different factors such as the terrain morphology, the wind farm area, the ind urbine size, the wind speed, the wind direction, and design of blades (Chen et al. , Ituarte-Villarreal and Espiritu 2011).

The wake effect is the key factor affecting the low efficiency of wind power production. It is very important to predict the relationship between the wake wind speed (wake effect) for various wind turbine and wind farm parameters.

If there is a lot of interference or wake generated by the wind turbines, the possibility of mechanical failure would increase as well as the need for more maintenance actions, and an inevitable reduction in power output. In addition to considering the impact of turbines on the others, it is important to take into account the terrain, weather conditions, and wind conditions in the region, such as speed and wind direction (Mokryani and Siano 2013;



To build a wind farm with the best features, it is desirable to select and analyze a subset of parameters that are truly relevant or the most influential to the wing turbine wake effect in order to minimalize the effect (Nagai et al. 2009; MacPhee and Beyene 2013).

This procedure is typically called variable selection, and it corresponds to finding a subset of the full set of recorded variables that exhibits good predictive abilities. In this study, architecture for modeling complex systems in function approximation and regresion was used, based on neural network. Neural networks can be defined as an architecture comprising massively parallel adaptive processing elements interconnected via structured networks. Thus, the neural network models generated from these data must therefore on how effectively the chosen sensor data represent the system. Therefore, in order to build a model that can predict a specific process output, it is desirable to specific subset of variables that are truly relevant to this output. This procedure is typically led variable selection, and it corresponds to finding a subset of the full set of the variables that exhibits good predictive abilities (Castellano and Fanelli 2000; Dieterle al. 2003; Cibas et al. 1996; Anderson et al. 2000). A solution to the variable section problem could be the utilization of prior knowledge in order to screen out the in vant variables. A more advanced approach is to consider the variable selection roblem as an optimization procedure via genetic algorithms (Donald 2002), where the objective is to minimize the error between the true values and the model predictions of the explained (output) variables, by selecting the proper explanatory (input) variables. e of the most powerful types of neural network system is adaptive neuro-fuzzy in. ence system (ANFIS) (Chan et al. 2011; Kwong et al. 2009).

The objective of variable selection . 'aree old: improving the prediction performance of the predictors, providing fast and have cost-effective predictors, and providing a better understanding of the underlyan process that generated the data, i.e., providing the most influential parameters on the predictor (Guyon and Elisseeff 2003; Despagne and Massart 1998; Papadokons ntaki, et al. 2005). Variable searching using the ANFIS network was performed to determine how the wind turbine and wind farm parameters affect the output wake w. speed. For the present study, analytical wake model named as Jensen's wal node (Jensen 1983) is chosen, because momentum is considered as conserved ins wake by this model. The analytical model was used for extracting training and che king data for the ANFIS network. ANFIS (Jang 1993), as a hybrid intellig interstem that enhances the ability to automatically learn and adapt, was used by researchers to modeling (Al-Ghandoor and Samhouri 2009; Singh et al. 2012; Petković 201); Petković and Čojbašić 2011), predictions (Hosoz et al. 2011; Khajeh et al. 009, Vakumar and Balu 2010), and control (Kurnaz et al. 2010; Ravi et al. 2011; d et al. 2010; Petković et al. 2012; Tian and Collins 2005) in various engineering stems. The basic idea behind these neuro-adaptive learning techniques is to provide a method for the fuzzy modeling procedure to learn information about the data (Aldair and Wang 2011; Dastranj et al. 2011). The ANFIS is one of the methods to organize the fuzzy inference system with given input/output data pairs (Wahida Banu et al. 2011; Grigorie and Botez 2009). This technique gives fuzzy logic the capability to adapt the membership function parameters that best allow the associated fuzzy inference system to track the given input/output data (Akcayol 2004; Shamshirband et al. 2010, 2014; Khoshnevisan et al. 2014).



2 Materials and methods

2.1 Project management method

Project development organizations are continually challenged by the need to improve the quality of the project products. Technologies are changing rapidly, and any project is becoming scalable and complex. In addition, large-scale, distributed development poses new challenges. To overcome the inability to meet the requirements and to deal with their rapid changing, project development requires the alignment of decisions on the strategie tactical, and operational levels (Moe et al. 2012). Project development also requires a transition from specialized skills to the redundancy of functions and from rational to naturalistic decision making. Likewise, Wysocki (2009) agreed that by using the wile software development method, there are many factors that will influence the success of a project. Agile method focuses on four manifestos, which are individual and iterations, working software, customer collaboration, and responding to change from us project, we adapt the responding to change manifesto.

To determine the wind turbine wake effect, the project must start by derstanding the wind farm efficiency model. The purpose is to indicate all jupper ant variables or parameters of the wind turbine. Every single of variable carries an equivion with factors to ensure the model efficiency. Table 1 shows the parameters and equations are not enough to maximize the power produced in a wind farm. New technique or system is required to having new variables selection that enables to not only maximize the wind turbine wake effect buy is capable to predict the efficiency. Then, ANFIS is chosen. The system works as a regre sion test as in a cyclic process, which changes of variables are made to ensure the best variables are selected.

2.2 Wind farm efficiency model

The wake expands linearly with downstream distance. The wake has a radius, at the turbine, which is equal to the turbine radius R_r , while R_1 is the radius of the wake in the model. R_1 is considered as radius of the downstream wake; the relationship between R_1 and X is that downstream one to e when the wake spreads downstream the radius R_1 ; that increases linearly, ropolitional, X. The wake expands linearly with downstream distance, as stated in Jens, 's and a shown in Fig. 1.

Following eq. ion is used to determine the wake wind speed (wake effect) after wind turbine row as it shown in Fig. 1:

wake effect parameters	s Inputs/output	Parameters description
	Input 1	X: wake downstream distance
	Input 2	R_r : wake or rotor radius
	Input 3	a: axial induction factor
	Input 4	z: hub height
	Input 5	z_0 : roughness of the surface
	Output	u: wake wind speed
	ikl	



In the above equation, we have

- u_0 is the mean wind speed or w. h can be explained as the free stream wind speed and in this study was used $u_0 = 12$ m.
- axial induction factor i denoted by *a*, which can be calculated from the $C_{\rm T}$, thrust coefficient. This can be corrained from the expression

$$C_{\rm T}=4a(1-a).$$

• X is consider that as the distance downstream of the turbine, while R_1 is related with R_r as represented using following equation:

$$R_1 = R_r \sqrt{\frac{1-a}{1-2a}}.$$

 α the entertainment constant and by using the following equation, it can be obtained as

$$\alpha = \frac{0.5}{\ln \frac{z}{z_0}}.$$

In the above equation, z is used to denote the hub height and roughness of the surface is denoted by z_0 . The value for surface roughness varies from field to field. For plain terrains, the value for $z_0 = 0.3$.

In this study, the used five variables are defined as in Table 1.

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Roughness class	Roughness length z_0 (m)	Energy index (%)	Land scape	
0	0.0002	100	Water surface	
1	0.03	52	Agricultural area, no fences or hedges, scattered buildings	
2	0.1	39	Agricultural area, couple of houses	
3	0.4	24	Villages, small town forests or very rough and uneven terrain	
4	1.6	13	Very large cities with tall buildings	

 Table 2
 Roughness classes and lengths

In the above Table 1, wake downstream distance X is in range 100–500 m w. or rotor radius is in range 10–40 m, axial induction factor is in range 0.2–0.4, at d hub height is in range 30–90 m. For parameter z_0 , five roughness classes of the surface w z_0 and yzed as listed in Table 2.

2.3 Variable selection using adaptive neuro-fuzzy inference system

Adaptive neuro-fuzzy inference system (ANFIS) can serve as a site for constructing a set of fuzzy "IF–THEN" rules with appropriate membership function to generate the stipulated input–output pairs. The membership functions are tunk at to the input–output data. ANFIS is about taking an initial fuzzy inference (FIS) system and tuning it with a backpropagation algorithm based on the collection of non-to-output data. The basic structure of a fuzzy inference system consists of three control tunk components: a rule base, which contains a selection of fuzzy rules; a database, which befores the membership functions used in the fuzzy rules; and a reasoning mechan and which performs the inference procedure upon the rules and the given facts to derive a reconable output or conclusion. These intelligent systems combine knowledge, technole, and methodologies from various sources. They possess human-like expertise within a specific domain—adapt themselves and learn to do better in changing environments. Fuzzy inference systems incorporate human knowledge and perform interfacing an environments.

Fuzzy logic plbox in MATLAB was used for the entire process of training and evaluation of zz inference system. Figure 2 shows an ANFIS structure for two inputs,



the most influential parameters on the wake wind speed and one output, estimated wake wind speed. Here, the analysis was constrained on the selection of two of the most influential parameters on the wake effect.

In this work, the first-order Sugeno model with two inputs and fuzzy IF–THEN rules of Takagi and Sugeno's type is used:

if x is A and y is C then
$$f_1 = p_1 x + q_1 y + r_1$$
.

The first layer consists of input variables membership functions (MFs), inputs 1 and 2. This layer just supplies the input values to the next layer. In the first layer, every node is an adaptive node with a node function $O = \mu_{AB}(x)$ and $O = \mu_{CD}(x)$ where $\mu_{AB}(x)$ and $\mu_{CD}(x)$ are MFs. In this study, bell-shaped MFs with maximum equal to 1 and minimum equal to 0 is chosen, such as

$$\mu(x) = \text{bell}(x; a_i, b_i, c_i, d_i) = \frac{1}{1 + \left[\left(\frac{x - c_i}{a_i}\right)^2\right]^{b_i}}.$$

where $\{a_i, b_i, c_i, d_i\}$ is the set of parameters set that in this layer e refer ed to as premise parameters. In this layer, x and y are the inputs to nodes and they prove the the combinations of the two most influential parameters of the wind turbine on the wer coefficient.

The second layer (membership layer) checks for the solution of each MFs. It receives the input values from the first layer and acts as MFs to represent the fuzzy sets of the respective input variables. Every node in the second layer is non-adaptive, and this layer multiplies the incoming signals and sends the product out like $w_i = \mu_{AB}(x) * \mu_{CD}(y)$. Each node output represents the firing strength of a sule.

The third layer is called the rule layer. Each 1 ode (each neuron) in this layer performs the precondition matching of the fuzzy r_{i} (s, i.e., they compute the activation level of each rule, the number of layers being c tal to the number of fuzzy rules. Each node of these layers calculates the weights which conormalized. The third layer is also non-adaptive, and every node calculates the ratio of the rule's firing strength to the sum of all rules' firing strengths like $w_i^* = \frac{w_i}{w_1+w_2}$, i = 1, 2. The outputs of this layer are called normalized firing strengths.

The fourth layer is valled the defuzification layer, and it provides the output values resulting from the inference of rules. Every node in the fourth layer is an adaptive node with node Ann $v_i = w_i^* x f = w_i^* (p_i x + q_i y + r_i)$ where $\{p_i, q_i, r\}$ is the parameter set and in the layer is referred to as consequent parameters.

The fifth over is called the output layer, which sums up all the inputs coming from the fourth layer and transforms the fuzzy classification results into a crisp (binary). The single node on the fifth layer is not adaptive, and this node computes the overall output as the ummation of all incoming signals

$$O_i^4 = \sum_i w_i^* x f = \frac{\sum_i w_i f}{\sum_i w_i}.$$

The hybrid learning algorithms were applied to identify the parameters in the ANFIS architectures. In the forward pass of the hybrid learning algorithm, functional signals go forward until layer 4 and the consequent parameters are identified by the least squares estimate. In the backward pass, the error rates propagate backwards and the premise parameters are updated by the gradient descent.

3 Results

A comprehensive search was performed within the available inputs to select the set of the most optimal combinations inputs (Table 1) that most influence the output parameter (wake effect). Essentially, the functions build an ANFIS model for each combination and train it for one epoch and report the performance achieved. In the beginning, the one most influential input in predicting the output was determined (Fig. 3). It can be seen that the wake downstream distance X has the most influence on the wake effect. The left-most input variable in Fig. 3 has the least error or the most relevance with respect to the output.

The plot and results from the function (Fig. 3) clearly indicate the input variable wak, downstream distance X as the most influential for wake wind speed prediction. The mining and checking errors are comparable, which indirectly suggests that there is no overning. This means it can be increased and explored to select more than one input parameter to build the ANFIS model. To verify this, search for the optimal combination of 2 input parameters can be performed.

The results in Fig. 4 indicate that input 1/input 2 (wake downstrying distance X/rotor radius R_r) forms the optimal combination of two input attributes for wake. Elect prediction. Further, search can be performed for the optimal combination of three input parameters. The results in Fig. 5 indicate that input 1/input 2/input 3 (way downstream distance X/ rotor radius R_r /axial induction factor a) forms the optimal combination of three inputs





attributes for wake effect prediction. Table 2 shows ANFIS regression errors for one input and for optimal combinations of the two and three inputs. It may not be appropriate to use more than two inputs for building the ANFIS model since a model with a simple structure was always preferred. Therefore, emphasis will be focused on the two input ANFIS for further examination. The selected input parameters from the original training and checking datasets were then extracted.





Fig. 7 Matlab SIMULINK block diagram for the estimation of wake wind speed

The used function for all parameters only trains each ANFIS for a single epoch to be able to quickly find the right inputs. Now that the inputs are fixed, and the number can be increased for epoch on ANFIS training (100 epochs) (Table 3).

The ANFIS input–output (decision) surface of the model for way wind peed (wake effect) is shown in Fig. 6. The input–output surface shown is a nonline r and monotonic surface, and illustrates how the ANFIS model will respond to arying the wake down-stream distance and wake or rotor radius or how the inputs and r use wake wind speed.

Two of the most influential wake effect parameters are implemented in MATLAB SIMULINK block diagram (Fig. 7) for fast estimation of very wind speed.

4 Conclusion

The main contribution of this research is a project management methodology with agile method, specific to the selection of wind robine wake effect most influential parameters, which helps with the strategic projection formulation, and is validated through the successful implementation of each of the proposed tools and activities.

Wind energy and conservently wind farms constitute one of the greatest renewable energy sources with rapid enclosion all over world. One of the main problems in the design and construction and wind farm, in order to maximize its energy production and its efficiency, is the optimal configurations of wind turbines to be installed. The grouping of turbines in a vind farm introduces two major issues: a wind turbine operating in the wake of another orbit. This a reduced power production and shortens the lifetime of the rotors. The additional turbulence in the wake could be a reason for increased material fatigue through flow induced vibrations at the downstream rotor. There are many parameters that have to be included in the wake effect prediction and estimation.

N. v parameters (input variables) define wake wind speed (wake effect) such as wake ownstream distance, rotor or wake radius, hub height, surface roughness, axial induction factor, and free wind speed as well. The inclusion of many input variables, however, has many drawbacks: explaining the model is difficult, irrelevant variables act as noise, and deteriorating the generalization capability of the model and data collecting can be much more costly. It is therefore useful to invent methods that allow reducing the number of input variables, thus reducing the complexity of the model, and possibly gaining better predictive performances and insights into the relevance of the variables for the problem.

In this study, a variable selection method using ANFIS network with cyclic agile method was performed to determine which wind turbine and farm parameters have the most influence on the wake wind speed. The two selected parameters were used as inputs to

ANFIS network for building a regression procedure to estimate the wake wind speed or wake effect.

Simulations were run in MATLAB, and the results were observed on the corresponding output blocks. The main advantages of the ANFIS scheme are computationally efficient, well adaptable with optimization and adaptive techniques. This can also be combined with expert systems and rough sets for other applications. ANFIS can also be used with systems handling more complex parameters. Another advantage of ANFIS is its speed of operation, which is much faster than in other control strategies; the tedious task of training MFs is done in ANFIS.

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